

FMS 2023 Automotive Panel – Memory Challenges for AV

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- 1.Endurance and Lifespan:** AVs operate for extended periods, accumulating a significant amount of data storage and retrieval.
- 2.Data Integrity and Retention:** The reliability of data storage is crucial for autonomous vehicles, especially in safety-critical applications.
- 3.Temperature and Environmental Considerations:** Avs are subject to varying temperature extremes and harsh environmental conditions.
- 4.Write amplification and Performance:** AVs require frequent write operations, such as logging sensor data, can lead to write amplification. Efficient wear-leveling algorithms and error correction techniques are crucial to mitigate write amplification and maintain optimal performance.
- 5.Security and Data Protection:** With autonomous vehicles generating and storing sensitive data, ensuring the security and protection of that data becomes paramount.
- 6.Functional Safety Compliance:** Autonomous vehicles are subject to stringent functional safety standards, such as ISO 26262.
- 7.Testing and Qualification:** Rigorous testing and qualification processes are necessary to ensure the reliability and adherence to performance specifications of flash memory in autonomous vehicles.

AV Memory Reliability Challenges → Longer POH

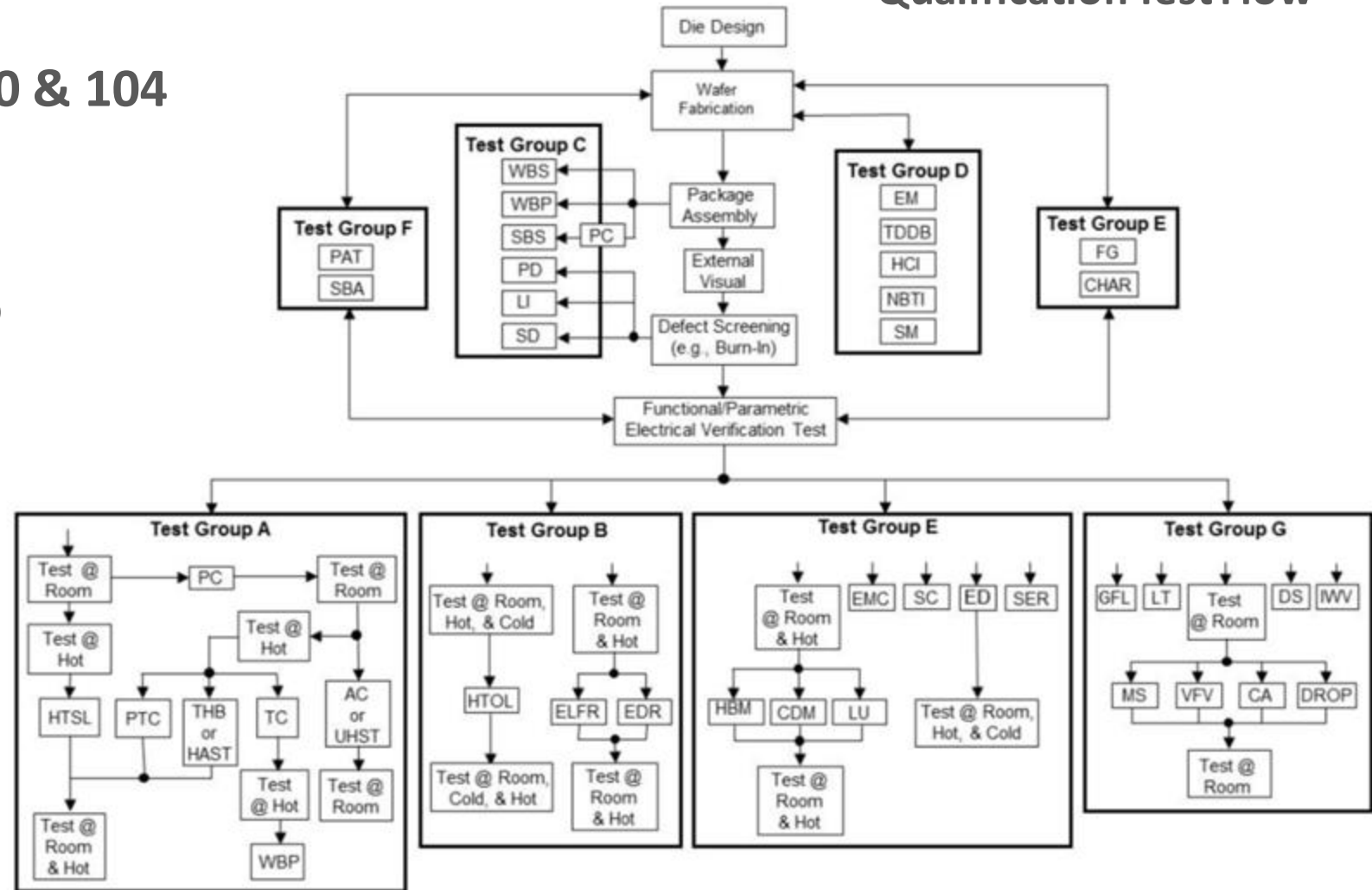
Memory Automotive Grade
Certification – Passing AEC-Q100 & 104

Key Requirements:

Zero failures from all the tests to
demonstrate 99% Rel at 90% CL

Question: Is current
AECQ spec adequate
to cover memory
qualification for AV &
EV applications?

AEC-Q100 Qualification Test Flow



Power-on Hour Mission Profile Gap

- Trends: on-time + standby time increase from traditional vehicle → EV → EAV
- Robo-taxi EAV will require 2-3x of life mileages as compared to consumer vehicles.

| Service Life = 15 years | 131,400 hours /150k miles |
|-------------------------|---------------------------|
| Driving - On | 10,000 hours |
| Inhibited - Off | 121,400 hours |



| Service Life = 15 years (EV) | 131,400 hours /150k miles |
|------------------------------|---------------------------|
| Driving - On | 8,000 hours |
| Charging - Standby | 30,000 hours |
| Inhibited - Standby | 67,000 hours |
| Inhibited - Off | 26,400 hours |



| Service Life = 5 years (EAV) | 43,800 hours / 400k miles |
|------------------------------|---------------------------|
| Driving - On | 34,675 hours |
| Charging - Standby | 5,475 hours |
| Inhibited - Standby | 1,825 hours |
| Inhibited - Off | 1,825 hours |

Current AECQ Covered
POH Target

Note: IC automotive technology: 10-20 years with 15% DF

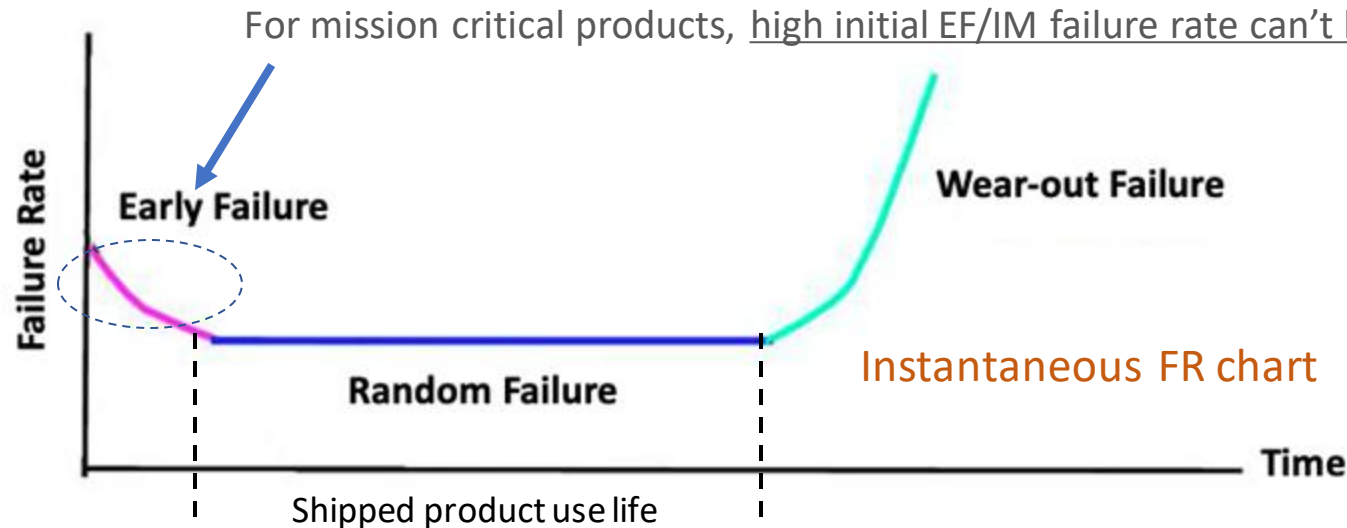
| Basic Lifetime Requirement | | | |
|----------------------------|---------------------|-------------|--------------|
| | Traditional Vehicle | EV | AV |
| Lifetime | 10-15 years | 15 years | 5 years |
| Operational Time | 8-10k hours | 38.5k hours | 40.15k hours |
| Operational Mileage | 150k miles | 150k miles | 400k miles |

* Robo-taxi has long daily operation hours or mileages so reduced vehicle lifetime.
* Robo-taxi AV requires higher reliability to meet operating lifetime & mileages!



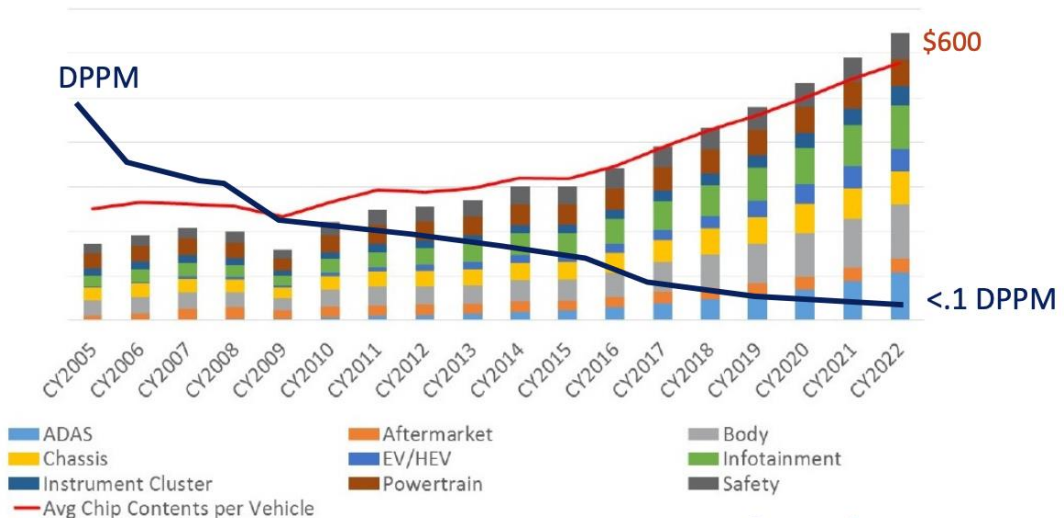
A gap exists!

AV Memory Quality Challenges → “Zero DPPM”



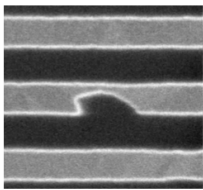
1. Achieving **“Zero Defect”** or virtual 0 DPPM/B
2. Proven reliability enablement from design awareness to process maturity as the “overkill” measures to demonstrate 0 DPPM/B

How to improve to achieve the Zero Defect Goal?

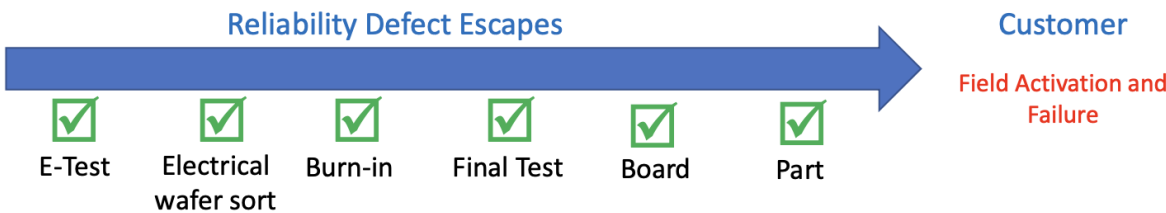


Source: Gartner

DPPM – Defective Parts Per Million



Fab



- **Process:** in-line optical defect detection, process variability control, stop excursion – 100% die screen, effective defect inspection, effective metrology
- **Electrical Test:** Go/No-Go decision ambiguity
 - * Latent defects aren't easily detectable at test.
 - * Untestable areas
 - * Coverage versus time-based costs.
- **PAT:** Parametric outlier analysis, but escapes might still happen